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Energy harvesting from vehicular traffic over speed bumps: A review

ABSTRACT

Energy used by vehicles to slow down in areas of limited speed is wasted. A Traffic Energy Harvesting Device (TEHD) is capable of harvesting vehicle energy when passing over a speed bump. This paper presents a classification of the different technologies used in existing TEHDs. Moreover, an estimation of the energy that could be harvested with the different technologies and their cost has been elaborated. The energy recovered with these devices could be used for marking and lighting of roads in urban areas, making transportation infrastructures more sustainable and environmentally friendly.

Keywords: Energy harvesting, speed bump, sustainable roads, traffic speed control.

1. INTRODUCTION

A speed control system (SCS) is a device used to slow down vehicles in certain stretches of roads. The first known SCS was placed in New Jersey in 1906 (Clement 1983). The dimensions of these devices are highly variable and can range from 5 to 15 centimeters high or even more. Similarly, the length can vary from a few centimeters to several meters. Systems around one meter or less in length are usually called "Speed Bumps", while those which are longer than a meter are called "Speed Humps" or "Speed Tables" if their upper part is flat. In 1975, the "Transport and Road Research Board" in the United Kingdom determined that the ideal design for these devices corresponds to a parabolic shape of 3.6 meters long and 10 centimeters high (Fig. 1) (Ansari Ardeh et al. 2008).

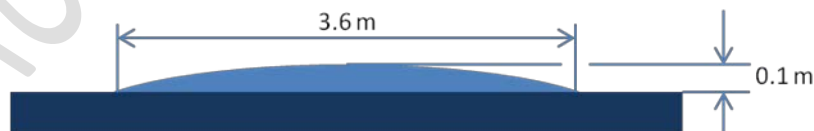


Figure 1: Parabolic hump profile

In the United States, the design guidelines developed by the Institute of Transportation Engineers suggest that the parabolic shape of 3.6 meters in length and 7.5 to 10 centimeters in height should be used as reference (ITE 1997). For the flat topped designs they recommend ramps of 1.83 meters long and 3.05 meters in length for the flat part (Bahar 2007). Other designs have been commonly used, such as the one which was installed for the first time at Seminole County in Florida State (Fig. 2). This design is flat in its upper part with a length of 6.6 meters and a height of 10 centimeters, with curved ramps of 1.8 meters in length (Ewing 1999).

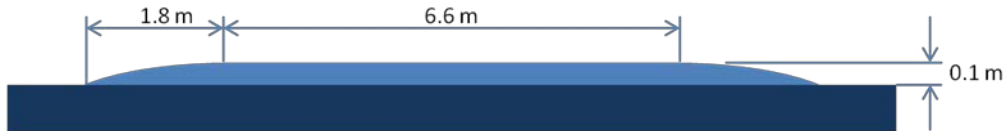


Figure 2: Seminole hump profile

36
37

38 Although the geometry of speed bumps and speed humps has been standardized in
 39 many countries, those standards vary greatly from ones to the others. For instance, in
 40 Spain this was not standardized until 2008 (Moreno et al. 2011). The Spanish standard
 41 distinguishes two sorts of SCSs: Speed Reducers, used to maintain a reduced
 42 circulation speed in certain stretches of roads, and Transversal Warning Bands, used
 43 to warn drivers of the need for some preventive action, such as reducing speed. There
 44 are two different design shapes in the Spanish standards for speed humps:
 45 trapezoidally-shaped ones of 4 meters in length in the upper part, ramps between 1
 46 and 2.5 meters long and 10 centimeters in height (Fig. 3); and circularly-shaped of 4
 47 meters in length and 6 centimeters in height (Ministerio de Fomento 2008), these are
 48 also named “humpback” due to their shape being very similar to the designs initially
 49 established as ideal in the UK and the US.

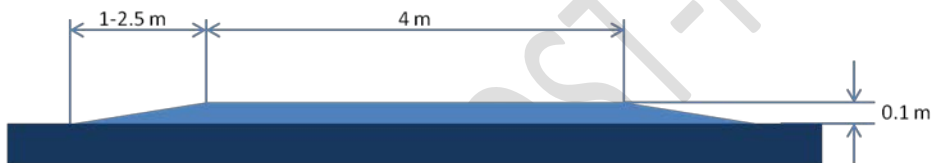


Figure 3: Trapezoidal hump profile

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51

52 In recent years the use of smaller-sized SCSs has increased. Although SCSs are very
 53 effective in reducing vehicle speeds and significantly decreasing the number of
 54 crashes, there are some drawbacks, such as the front wheels taking off when the
 55 vehicle drives at excessive speed, unpleasant vibrations for passengers at speeds
 56 below the limit, failure to transmit strong vibrations when vehicles pass at an
 57 inadequate speed, forcing all the drivers to slow down, and inconvenience created to
 58 emergency vehicles such as ambulances and fire trucks (Ansari Ardeh et al. 2008;
 59 Khorshid et al. 2007).

60 In order to enhance all these aspects, in recent years several research works have
 61 been carried out worldwide to optimize the design of SCSs, relating the different
 62 variables involved in the design of these systems: speed, height, length, radius of
 63 curvature and vertical acceleration experienced by the vehicle and passengers at the
 64 time of contact (Başlamışli & Ünlüsoy 2009). This has led to the establishment of a
 65 general design criteria for SCSs; nevertheless, there are still many different designs
 66 and rules depending on country or local authorities (Weber & Braaksma 2000).

67 From the point of view of traffic energy harvesting, the SCS typology that suits better
 68 with a TEHD is a speed bump. Speed humps are too large for this purpose and the
 69 required device would present problems due to its dimensions, weight and complexity.

70 This document presents the state of the art of the energy harvesting from vehicular
 71 traffic over a speed bump. This process should try to take advantage of the vehicles'

72 energy when passing over SCSs in the limited speed areas, and use it for lighting and
 73 marking of those roads. It should also take into account the comfort and safety
 74 standards for the vehicles and passengers, as well as avoiding the increase in the
 75 power consumption of the vehicle.

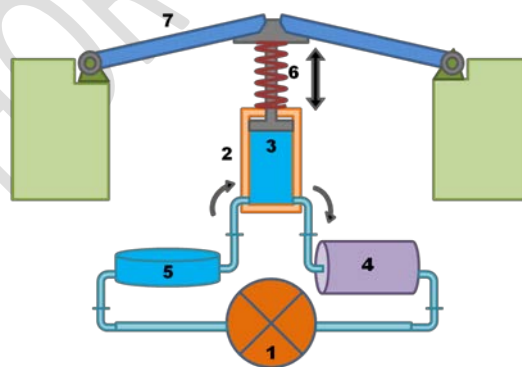
76 2. ENERGY HARVESTING TECHNOLOGIES CLASSIFICATION

77 A traffic energy harvesting device (TEHD) is capable of transforming the motion and
 78 pressure generated by a passing vehicle into useful energy. There are different
 79 technologies capable of harvesting energy from vehicles passing over a speed bump.
 80 These technologies differ in the way of harvesting energy and its conduction, since all
 81 of them use an electromagnetic generator except piezoelectric devices.

82 The proposed classification of existing devices is based on these different energy
 83 harvesting technologies, and how they are used to transform energy from vehicles into
 84 useful electric energy. Around one hundred different patents and other intellectual
 85 properties have been consulted. There are many similar devices that only differ in
 86 some details, accordingly only the most representative have been selected for this
 87 classification due to its characteristics, date of publication or importance.

88 2.1. HYDRAULIC TEHDs

89 An elemental hydraulic TEHD comprises a piston, cylinder, pipes and a hydraulic
 90 turbine. They are based on Bernoulli's principle, the compressed fluid inside the piston
 91 goes into the external pipes decreasing its pressure but increasing its velocity, due to a
 92 cross-section reduction. A hydraulic turbine transforms the fluid speed into mechanical
 93 energy and then into electricity (Fig. 4) (Esteban et al. 2006).



94

95 Figure 4: Hydraulic TEHD working scheme. Main components: (1) Hydraulic turbine, (2) Cylinder, (3)
 96 Piston, (4) Accumulator, (5) Reservoir, (6) Damper and (7) Ramp.
 97

98 Table 1: Patents of hydraulic TEHDs

Title	Publication number	Author(s) ^a
Method and apparatus utilizing the weight of moving traffic to produce useful work	US4339920 (A)	Le Van (1982)
Road speed limiting device	AU712078 (B2)	Follman (2000)
Electrical energy producing platform and method of use	US6172426 (B1)	Galich (2001)

Hydraulic roadbed electricity generating apparatus and method	WO2007013998 (A3)	Adair (2007)
Vehicular hump for electric energy production	WO2009037559 (A3)	Callegari (2009)
Traffic actuated electrical generator apparatus	US7629698 (B2)	Horianopoulos (2008)
Adaptive vehicle energy harvesting	US2010198412 (A1)	Hendrickson (2010)
Driving an electricity generator using the kinetic, gravitational or air pressure forces present in the flow of vehicular or pedestrian traffic or sea waves	GB2461860 (A)	Dunn (2010)
Hydraulic electromagnetic generation device for collecting idle kinetic energy of vehicles	CN102536691 (B)	Guoqin et al. (2012)
Speed bump capable of electricity generation	KR101256817 (B1)	Cho et al. (2012)
Apparatus for generating electric power using hydraulic including speed bump	KR101236343 (B1)	Kim Jang et al. (2013)
Water-power flexible speed bump	CN203229881 (U)	Ren et al. (2013)

99

^aPatents' references

100 In the TEHD designed by Le Van (1982), when a vehicle passes over the device, it
 101 exerts pressure on a chamber filled with incompressible fluid. This chamber is
 102 connected to a circuit with unidirectional control valves to drive the fluid into a motor.
 103 Follman (2000) presents two possible configurations, in both cases the passage of the
 104 vehicle over the ramp compresses a piston that pushes the fluid from inside the
 105 cylinder to a storage system. The cylinder has input and output valves to control the
 106 fluid flow during the compression and expansion stage. A generator connected to the
 107 storage system provides electricity to the network.

108 The idea of Galich (2001) is a compressible bed filled with incompressible fluid placed
 109 under the road surface. This fluid is pushed by the vehicles weight into a circulation
 110 system where fluid energy is transformed into mechanic energy and through a
 111 generator into electricity.

112 Adair (2007) proposes a TEHD with a movable plate that descends over a piston,
 113 pushing the incompressible fluid from the cylinder into an electric generator. There are
 114 two recovery systems for the piston: in the first, a spring connected to the plate returns
 115 the piston to its original position, and in the second, an expansion tank placed between
 116 the cylinder and the generator drives the fluid to the cylinder, pushing the piston to its
 117 original position. The TEHD designed by Callegari (2009) comprises a pyramidally-
 118 shaped movable cover that compresses some oleo dynamic cylinders filled with
 119 hydraulic fluid or oil. The fluid is pumped into an oleo dynamic motor connected to a
 120 current generator.

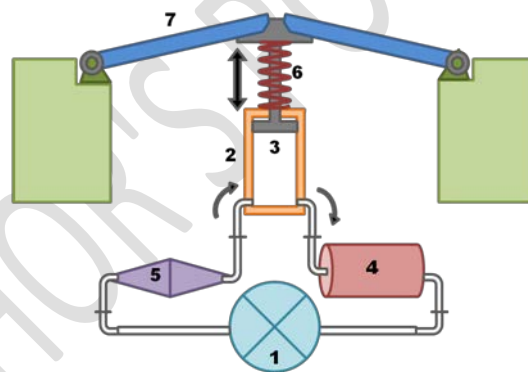
121 Horianopoulos (2008) proposes a system with a low-pressure fluid reservoir, a high-
 122 pressure fluid accumulator and at least one recovery device placed under the road
 123 surface. When traffic passes over, the device pumps the fluid from the reservoir to the
 124 accumulator. The high-pressure fluid can be used later to supply an electric generator.
 125 The cover shape can be cylindrical or trapezoidal. The system designed by
 126 Hendrickson (2010) is made up of four units: in the first, there is a control device to
 127 measure the speed and weight of the vehicle; the second unit calculates an
 128 acceleration or deceleration range using the speed measured; the third unit compares
 129 the measurements and the forth unit adjusts the system reaction as a function of the
 130 results from the third unit. These units adjust the resistance offered to the vehicle
 131 passage, making the system more efficient. Energy is harvested with a flexible device

132 full of fluid. When a vehicle passes over it, the fluid is pushed into a hydraulic motor to
 133 generate electricity.

134 KinergyPower Corporation (2012) presents several devices for energy harvesting from
 135 vehicles and pedestrians. The cover of the systems is made up of many small plates.
 136 When a vehicle passes over, these compress the pistons placed underneath each
 137 plate. At the same time each of these pistons push the fluid into a system where it is
 138 stored in accumulators filled with gas and fluid. These accumulators allow the system
 139 to store the fluid and supply it to the generator later. The fluid used by the generator is
 140 returned to a tank at atmospheric pressure, ready to be used in the pistons again. The
 141 dimensions and shape of the system vary with the type of traffic. The KinerBump for
 142 light traffic is trapezoidally-shaped, of 8 meters in length and 9 centimeters in height
 143 (KinergyPower 2012).

144 2.2. PNEUMATIC TEHDs

145 The working principle of a pneumatic TEHD is similar to a hydraulic one but with gas or
 146 air instead of incompressible fluid. It is obvious that if the gas or air is introduced under
 147 atmospheric conditions in the piston, all the compressive force would be used to
 148 compress the air and the efficiency of the process would be really low. Hence it is
 149 necessary to compress the gas or air beforehand, which implies the need to use a
 150 compressor (Fig. 5) (Croser & Ebel 2000).



151

152 Figure 5: Pneumatic TEHD working scheme. Main components: (1) Generator, (2) Cylinder, (3) Piston, (4)
 153 Accumulator, (5) Compressor, (6) Damper and (7) Ramp.

154 Table 2: Patents of pneumatic TEHDs

Title	Publication number	Author(s) ^a
Apparatus for compressing gas in response to vehicular traffic	US4081224 (A)	Krupp (1978)
Vehicle-actuated air compressor and system therefor	US4173431 (A)	Smith (1979)
Traffic-operated air-powered generating system	US4212598 (A)	Roche & Banks (1980)
Power generation device of speed reducing plate for vehicle	CN102588234 (A)	Xuchen (2012)
Electric generator using speed bump	KR101258233 (B1)	Kim Jae (2012)

155 ^aPatents' references

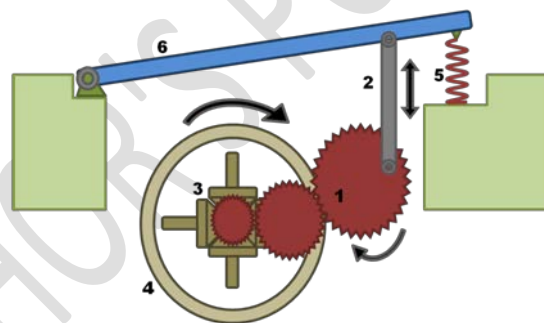
156 Krupp (1978) presents a TEHD with a set of small bumps along a stretch of the road. A
 157 chamber filled with gas is placed underneath each bump. The upper wall of the
 158 chamber is flexible to facilitate gas compression due to the vehicle weight. All

159 chambers are connected in series in order to push the gas from one chamber to the
 160 next which is at a higher pressure. The last chambers of the set have a smaller flexible
 161 area to increase the pressure exerted by vehicle weight. This highly pressurized air can
 162 be used to generate electricity through a turbine. Smith (1979) proposes a TEHD with a
 163 small bump in the road surface that compresses a piston when the vehicle passes over
 164 it. The device returns to its original position using two springs on the two sides of the
 165 cylinder where the air is compressed. The piston comprises input and output valves to
 166 allow the entrance of air during the piston elevation and the expulsion in the descent.
 167 There is an air pressurized accumulator between cylinders and the generator.

168 Another TEHD is proposed by Roche & Banks (1980). The cover is a hinged panel that
 169 descends and compresses an air pump. There are two different pumps for this
 170 purpose, compressible cylinders placed across the road surface or a piston with a
 171 cylinder. Control valves are included to avoid air leaks. An air compressor supplies the
 172 air to the cylinders at a suitable pressure, avoiding energy losses in the compression
 173 process. The air drives a turbine that provides rotation energy to a generator.

174 2.3. MECHANICAL TEHDs

175 The basic principle of this sort of harvesters is to transform mechanic force into
 176 electricity using a mechanism. There are many different designs; the most commonly
 177 used are mainly made up of connection rods, crankshaft and gears to maximize the
 178 rotational speed inside the generator (Fig. 6) (Saneifard et al. 2009).



179

180 Figure 6: Mechanical TEHD working scheme. Main components: (1) Gears, (2) Connecting rod, (3) Rotor,
 181 (4) Stator, (5) Damper and (6) Hinged platform.

182 Table 3: Patents of mechanical TEHDs

Title	Publication number	Author(s) ^a
Vehicle actuated, roadway electrical generator	US4614875 (A)	McGee (1986)
Energy generation system and method	AU2003256053 (A1)	Alperon (2004)
Road deceleration strip generating set	CN101285455 (B)	Kun et al. (2008)
System and method for electrical power generation utilizing vehicle traffic on roadways	US2011148121 (A1)	Kenney (2009)
Vehicular movement electricity converter embedded within a road bump	WO2008035348 (A3)	Chen (2010)
Highway speed bump energy power generating device	CN201448203 (U)	Kunyi (2010)
Road way new energy	KR20100052583 (A)	Hwangbo (2010)
Generator by rack and pinion gear	KR20110079798 (A)	Kim Weon (2011)

Self-energy generating road speed bump that distinguish is practicable night	KR20120004062 (U)	Park (2012)
Self-generator of speed hump	KR101345562 (B1)	King Nag (2013)
Vibration generating set and road speed bump with same	CN103696918 (A)	Wang et al. (2014)
Vertically movable electricity generating device for road speed bump	CN203584698 (U)	Ma & Yan (2014)

183 ^aPatents' references

184 McGee (1986) proposes a TEHD with a pyramid-shaped cover, which when the vehicle
185 passes over the device, depresses the vertex and activates different gears,
186 transforming the descent of the cover into rotational movement. In the TEHD designed
187 by Alperon (2004) a cylinder partially embedded in the road surface rotates when a
188 vehicle passes over it. This rotation activates a gear system and maximizes the rotation
189 speed in the generator.

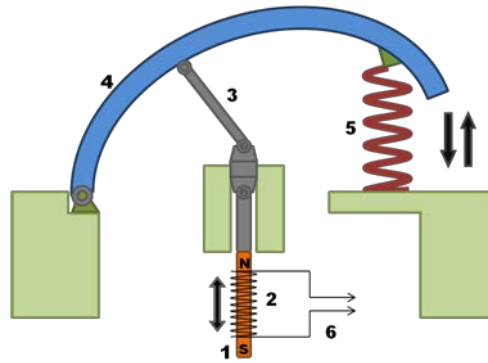
190 Kenney (2009) uses two movable plates assembled with a rocker arm, when the
191 vehicle passes over the first plate it descends and moves the rocker arm. In the same
192 way the second plate returns the rocker arm to its initial position. A generator uses this
193 swinging movement to produce electricity. Another similar TEHD is proposed by Chen
194 (2010). In this device, a semi flexible cover protects the rest of the components. When
195 the vehicle passes over the cover, it depresses a wing and engages a clutch
196 transferring the rotational motion through a flywheel to the rotor of the generator.

197 Saneifard et al. (2009) presented the experimental results obtained with the device
198 fabricated by their team in the Journal of Engineering Technology. In the device's
199 upper part there is a movable road plate. There is a damping system to return the plate
200 to its original position. When the vehicle passes over the plate, connecting rods transfer
201 this movement to the crankshaft and this to the gears. Finally the rotation reaches the
202 generator, where it is transformed into electrical energy.

203 Another TEHD is the Electro Kinetic Road Ramp, presented on its website by Highway
204 Energy Systems Ltd (2011). The generation system is comprised of connecting rods,
205 crankshaft, flywheel, gears, generator and a storage system. On the surface there are
206 three assembled road plates that move like a wave when the vehicle passes over
207 them. Tests performed with this ramp were satisfactory and it was placed in some outer
208 London areas in 2009 (Highway Energy Systems 2011).

209 **2.4. ELECTROMAGNETIC TEHDs**

210 The electromotive force induced in a circuit is proportional to the variation of the
211 magnetic field flux with time in that circuit. There are two main types of electromagnetic
212 generator, linear and rotational. Most generators used today are based on rotation and
213 are used in numerous applications, from large-scale power generation to small
214 applications for recharging batteries (Harb 2011; Mitcheson et al. 2008). Figure 7
215 shows a model of a generic electromagnetic TEHD.



216

217 Figure 7: Electromagnetic TEHD working scheme. Main components: (1) Magnet, (2) Coil, (3) Connecting
 218 rods, (4) Movable cover, (5) Damper and (6) Circuit.

219 Table 4: Patents of electromagnetic TEHDs

Title	Publication number	Author(s) ^a
Vehicle-actuated road imbedded magneto generator	US7102244 (B2)	Hunter (2006)
Electro-gravity plates for generating electricity from passage of vehicles over the plates	US7589428 (B2)	Ghassemi (2008)
System and method for generating electricity from automobile traffic	US2009173589 (A1)	Nejmeh (2009)
Electric power generating apparatus by using the impact energy of road bump on the road	KR20110017142 (A)	You et al. (2011)
Electricity generation and storage device for road speed bump	CN201466944 (U)	Yuansheng et al. (2012)
Pavement motive power generation device	CN202250645 (U)	Yunhua & Daliang (2012)
Electric power generating speed bump	US2013193692 (A1)	Dimitriev (2013)
System for converting potential or kinetic energy of a body weighing upon or travelling over a support or transit plane into useful energy	US8901759 (B2)	Pirisi (2014)

220 ^aPatents' references

221 The TEHD designed by Hunter (2006) proposes a series of transverse bands
 222 embedded in the pavement with magnets inside them. When the vehicle passes over
 223 the bands, it depresses the solenoids and induces electric current in them. The device
 224 returns to its original position due to a spring placed in the bottom part of the
 225 mechanism. Ghassemi (2008) proposes a similar TEHD. When the platform descends,
 226 the magnet passes through a solenoid and induces an electric current. On both sides
 227 two cushions are adjusted ensuring the rebound and return of the platform to its
 228 original position for the next vehicle.

229 Nejmeh (2009) proposes electricity generation taking advantage of the existing metals
 230 inside the vehicles. The TEHD is composed of cylindrical devices with a fixed stator in
 231 the inner part where the windings are located, and a movable rotor with magnets in the
 232 external part. The external perimeter of the rotor is slightly underneath the road
 233 surface. In this way, when vehicles pass over the devices, a magnetic force will appear
 234 between the metal components of the vehicles and the magnets of the rotor,
 235 generating a movable magnetic field that induces a current in the stator windings.

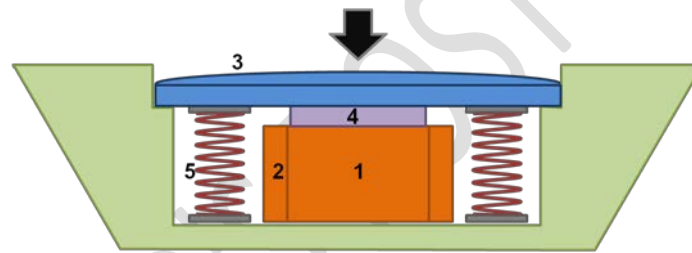
236 The design of You et al. (2011) has a circular cover in its upper part connected to a
 237 spring that absorbs the vehicle weight and returns the cover to its initial position. At the

238 same time, the cover is connected to an electromagnetic device by a connecting rod.
 239 When the cover descends a magnet moves into a coil and this generates electricity.

240 Finally, Pirisi (2014) presents a system with an optimization of a tubular permanent
 241 magnet linear generator. This optimization is developed using hybrid evolutionary
 242 algorithms, reaching the best overall system efficiency and minimizing the impact on
 243 the environment and transportation systems.

244 2.5. PIEZOELECTRIC TEHDs

245 Piezoelectricity is a result of the microscopic properties of certain materials. The
 246 phenomenon occurs because when applying mechanical stresses, crystals acquire an
 247 electric polarization. This causes a potential difference and the appearance of opposite
 248 electrical charges on their surfaces (Khaligh et al. 2010; Cook-Chennault et al. 2008).
 249 Lead Zirconate Titanate (PZT) ceramics were discovered in 1954 and since then
 250 replaced barium titanate ceramics as the dominating material in all fields of
 251 piezoelectric applications. There are two main types of piezoelectric energy harvesting
 252 devices: piezoelectric stack transducers (Fig. 8) and piezoelectric bender transducers
 253 (Fig.9) (Nuffer & Bein 2006).



254

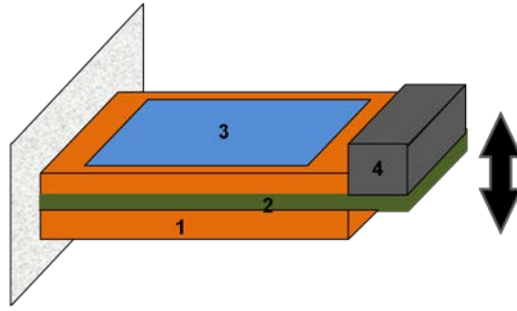
255 Figure 8: Piezoelectric stack TEHD working scheme. Main components: (1) Piezoelectric plates, (2)
 256 Electrodes, (3) Platform, (4) Clamp and (5) Dampers.

257 Table 5: Patents of piezoelectric TEHDs

Title	Publication number	Author(s) ^a
Electro-gravity plates for generating electricity from passage of vehicles over the plates	US7589428 (B2)	Ghassemi (2008)
Speed bump capable of generating power	CN202039306 (U)	Hao (2011)
Multi-layer modular energy harvesting apparatus, system and method	US8278800 (B2)	Abramovich et al. (2012)
Piezo electromechanical device for recovering energy from vehicle transit	ES2488871 (T3)	Salvini et al. (2014)

258 ^aPatents' references

259 The TEHD proposed by Ghassemi (2008) is made up of several rows of plates
 260 containing a piezoelectric material. Above these plates there is a platform and when it
 261 descends, an attached clamp compresses the piezoelectric device (Fig. 8), thus
 262 obtaining electrical charge. At both sides of the plates two cushions are set ensuring
 263 the rebound and return of the platform to its original position for the next vehicle.



264

265 Figure 9: Scheme of a piezoelectric bimorph cantilever beam generator: (1) PZT plates, (2) Shim layer, (3)
 266 Electrode and (4) Tip mass.

267 Messineo et al. (2012) presents a TEHD using a piezoelectric bender device. The
 268 prototype consists of an external box embedded in the pavement and an internal box
 269 connected by elastic elements. This mechanical configuration allows transferring the
 270 vibration produced by the inner box descending to the piezoelectric bender transducer.
 271 The flexibility of the system configuration allows modifying the oscillation frequency in
 272 order to match the optimal resonance frequency of the PZTs.

273 Recently, a significant number of piezoelectric energy harvesting applications have
 274 been developed to produce electricity from vehicular, train or pedestrian traffic. For
 275 instance, the East Japan Railway Company has developed an energy-generating floor
 276 to power Tokyo subway ticket gates and display systems. It is expected that this system
 277 provides 1400 Kw per day for an area of 25 square meters.

278 Finally, the most known system was developed by the Israeli company Innowattech. In
 279 this patent (Abramovich et al. 2010), piezoelectric stack transducers are embedded in
 280 the asphalt along the road. The energy used in road deformation is transformed into
 281 electric energy through a direct piezoelectric effect. Innowattech (2012) developed and
 282 tested this technology and they have collaborated in a project with the Israeli National
 283 Road Company (INRC).

284 3. CRITICAL REVIEW OF EXISTING TECHNOLOGY

285 The aim of this section is to assess the different aspects to take into account when
 286 designing a TEHD and make a comparison among the technologies used in these
 287 devices.

288 3.1. POWER OUTPUT

289 The evaluation of the exact amount of energy that could be harvested with the different
 290 TEHDs is a complicated task due to the lack of technical data from patents and other
 291 existing devices. Assuming that all the TEHDs have the same energy input, it is
 292 possible to calculate an approximate value for the electric power output. For this
 293 purpose some assumptions and experimental values from other documents are used in
 294 addition to the corresponding theory. The results obtained can be used to compare the
 295 systems and optimize the selection for each different situation.

296 Piezoelectric and electromagnetic technologies are capable of generating more power
 297 when they vibrate. Through the adequate mechanism, it is possible to generate a
 298 vibration with an optimal frequency, thereby maximizing the power obtained by these
 299 TEHDs (Roundy et al. 2003; Cannarella et al. 2011). According to this, the power
 300 output values adopted for the piezoelectric and electromagnetic TEHDs will correspond
 301 to vibrating systems. The vehicle adopted for all the cases is a standard medium-sized
 302 car with a weight of 1800 Kg and the SCS has a height of 8 centimeters.

303 According to Phalke (2011), for a piezoelectric device of the ceramic PZT 5H type and
 304 a vibration frequency of 148.904 Hz, the power obtained is 87.06 μ W.

305 This power is for only one piezoelectric device, but due to its reduced dimensions and
 306 depending on the measurements of the SCS, it would be possible to place between
 307 250 and 350 devices. See Table 6.

308 Zuo et al. (2010) carried out tests with an electromagnetic device similar to what could
 309 be placed in a SCS. This system comprises only one coil and supplies average
 310 voltages of 10 V and 2 W with a frequency of 10 Hz. Similarly to the piezoelectric case,
 311 taking into account the dimensions, it would be possible to place between 10 and 20
 312 devices (Table 6).

313 A hydraulic TEHD with suitable dimensions to be placed in a SCS is described by Arizti
 314 (2010). This device with a cylinder of 55 mm diameter, output holes of 10 mm diameter
 315 and an internal pressure of 350 bars, supplies an average power of around 800 W. A
 316 pressure of 350 bars is far higher than what a vehicle could generate in passing over a
 317 SCS. Taking the same cylinder and for a vehicle weight of 1800 Kg, the pressure inside
 318 the cylinder is:

319
$$(1) P = 1800 \text{ Kg} * 10 \text{ m/s}^2 / 0.002375 \text{ m}^2 \approx 7600000 \text{ Pa}$$

320 This pressure is nearly a fifth of Arizti's value (Arizti 2010). It is assumed that the
 321 pressure in the cylinder has a direct relationship with the output power (Table 6).

322 A pneumatic TEHD is not contemplated because its operation is analogous to the
 323 hydraulic one but less efficient due to loss in the compression of the gas. Furthermore,
 324 a compressor that consumes energy is necessary.

325 In the mechanical TEHD built by Saneifard et al. (2009), the performance of the device
 326 is well described. The shaft of the generator rotates at 3537 revolutions per minute,
 327 generates 12 A of current and a voltage of 12 V. This supplies a power peak of 144 W
 328 per vehicle.

329 Table 6: Performance of the different TEHDs for the defined boundaries

TEHD Technology	Performance ^a (W per vehicle)	Notes
Hydraulic	160-200	Calculated from the device of Arizti (2010) assuming linear behaviour.
Electromagnetic	20-40	Quoted for Zuo et al. (2010) device at a vibration frequency of 10 Hz.
Piezoelectric	22-30	Quoted for a ceramic PZT 5H at a vibration frequency of 150 Hz.

330 ^aThese numbers depend heavily on the specifications of the different technologies

331 Based on the available data, the defined boundaries and the corresponding theoretical
332 formulas, it is possible to do an appraisal of how the speed bump step height,
333 vehicle weight and speed could affect the power output of the different TEHDs.
334 Because of its configuration and working principles a hydraulic TEHD would be more
335 affected by a variation in the vehicle weight than other devices. In the case of
336 piezoelectric and electromagnetic TEHDs, this depends on whether the variation in the
337 vehicle weight affects the vibration mechanism and hence the vibration frequency. If
338 the speed of the vertical movement does not affect the vibration frequency, the
339 influence of the vehicle weight on the TEHD efficiency would be negligible.

340 Likewise the height of the SCS is important. Its variation would enhance the
341 performance in all cases, being more important in the hydraulic and electromagnetic
342 TEHDs.

343 The vehicles' passage at an excessive speed in no case would lead to an
344 improvement, due to the decrease of the pressure over the device. In fact, the front
345 wheels could take off from the road surface, resulting in an incomplete descent of the
346 device and hence a loss of efficiency.

347 Other important factors to take into account are traffic intensity and heavy vehicles'
348 percentage. These factors would have different effects depending on the TEHD used.
349 For instance, a high percentage of heavy vehicles would produce significantly more
350 power for hydraulic TEHDs but could be negligible for other devices. A SCS could slow
351 down traffic significantly in a residential area with low traffic intensity, whereas in a road
352 with high traffic intensity the device must be easily affordable. A more affordable SCS
353 usually implies less harvested power per vehicle, but more vehicles and vice versa.
354 Hence, it will be very important to study all these factors in order to optimize the most
355 suitable selection in each case. This suggests the possibility of using a mixed system
356 capable of combining different types of technologies: taking advantage both of the
357 potential energy and vertical movement and leading to a more efficient system. For
358 instance, Salvini et al. (2011) proposes a TEHD with electromagnetic and piezoelectric
359 technologies. When a vehicle passes over the device, a magnet goes through a coil
360 and induces a current in it. At the same time, the weight of the vehicle compresses and
361 deforms the piezoelectric material, producing electric voltage.

362 **3.2. STORAGE**

363 Vehicular traffic is not a continuous energy source due to its intermittence. Hence it is
364 necessary to use a storage system to take advantage of energy obtained in moments
365 with high traffic intensity and supply it when necessary. The main storage systems are
366 batteries and ultra-capacitors.

367 Batteries are the most commonly used devices for storing electric energy. Although in
368 the beginning batteries had a low efficiency, in recent years there has been a
369 breakthrough in development of Ion-Lithium and Lithium-Polymer batteries. These

370 batteries have a significantly better performance than any other batteries made of other
 371 materials with the only drawback of their high cost, although in recent times this is less
 372 a problem because of continuous advances in this technology (Burke & Miller 2011).
 373 The new generations of ultra-capacitors fabricated with carbon derivatives can supply
 374 more electric power than batteries, and moreover, there is no chemical reaction inside,
 375 and hence there is not deterioration with the use cycles (Guan and Liao 2008).

376 Batteries have a specific energy an order of magnitude higher than ultra-capacitors,
 377 and can supply energy during a longer time period (Baisden & Emadi 2004). On the
 378 other hand, ultra-capacitors have a specific power an order of magnitude higher than
 379 batteries, and can supply higher power peaks (Nzisabira et al. 2009). As for life span,
 380 batteries lose their efficiency with about a few thousand cycles; while ultra-capacitors
 381 are able to maintain their performance for more than a million cycles (Guan & Liao
 382 2008). Ultra capacitors charge and discharge efficiency; that is, the relationship
 383 between the energy used to charge it and the energy the device can supply, is about
 384 85 to 98% depending on the cases, while for batteries it is between 50 and 85% in the
 385 best cases (Table 7). When the current to be supplied is constant and with few power
 386 peaks batteries have a good efficiency and life span, reducing the energy demand from
 387 the source (Baisden & Emadi 2004).

388 Table 7: Comparison between battery and ultra-capacitor capabilities ^a (Baisden and Emadi, 2004; Burke
 389 and Miller 2011)

Storage Device	Specific Power (W/Kg)	Specific Energy (W-h/Kg)	Supplying Time (s)	Life Span (Cycles)	Charge / Discharge Efficiency (%)
Battery	<1000	<150	<10000	10 ³	50-85
Ultra Capacitor	<10000	<15	<100	10 ⁶	85-98

390 ^aThese numbers can vary for some devices

391 The complementary characteristics demonstrated by batteries and ultra-capacitors
 392 suggest that they could be combined to create an integrated system. Recent research
 393 shows that a system with batteries and ultra-capacitors leads to better performance
 394 than a similar system with only one type of device. The combination of batteries and
 395 ultra-capacitors results in more compact and lighter systems, with a good relationship
 396 between power and energy. Furthermore, this combination allows the reduction of the
 397 required battery size, thus obtaining a weight and cost reduction, and a longer life span
 398 (Bubna et al. 2012; Burke & Miller 2011).

399 3.3. COST AND FEASIBILITY

400 A cost estimation of the different TEHDs has been made assuming some approximate
 401 values to obtain an order of magnitude of the actual cost. This cost varies greatly
 402 between devices depending on the materials and technology used. In this value, only
 403 the cost of the TEHD is included. The installation, cover and other components are not
 404 taken into account, being similar for all of them and not as significant as TEHD's cost,
 405 except for the size of the elements and installation that usually would be higher for
 406 larger devices.

407 The piezoelectric device described by Phalke (2011) costs up to 40 € in the current
 408 market. The number of devices used for calculations in paragraph 4.1 is assumed
 409 (Table 8).

410 An electromagnetic linear generator with the suitable characteristics could cost up to
 411 1000 € (Table 8) (Danielsson 2003).

412 A hydraulic turbine model R-125 or CJ-750W with suitable characteristics has a cost of
 413 nearly 2000 €. Also, it is necessary to add the cost of other required components such
 414 as cylinders, reservoir, accumulator and valves (Table 8) (3HC Centrales
 415 hidroeléctricas 2011).

416 The mechanical device built by Saneifard et al. (2009) costs up to 2000 €.

417 Table 8: Estimated payback period for the different TEHDs

TEHD Technology	Hydraulic	Electromagnetic	Piezoelectric	Mechanical
Initial Investment ^a (€)	10000	15000	12000	2000
Savings per year ^b (€)	3000	1500	1800	2400
Payback period (years)	3.3	10	6.6	0.8

418 ^a These numbers represent the additional value over a standard SCS and depend heavily on the specifications of the
 419 different technologies.

420 ^b These numbers have been calculated for a traffic intensity of 45000 vehicles per day and a cost of 0.06 €/KWh.

421 Results from Table 6 and 8 show that hydraulic and mechanical technologies supply
 422 more average power per vehicle and also have an average lower initial investment.
 423 This is in agreement with the number of devices studied to elaborate the classification,
 424 hydraulic and mechanic TEHDs being the most numerous. Nevertheless, the latest
 425 advances in materials like piezoelectric plates have caused an enhancement of their
 426 performance and a decrease in their cost. Thus depending on other factors, the
 427 placement of other technologies may be more feasible. For instance, hydraulic and
 428 mechanical devices are significantly larger than the others and cannot be placed in
 429 areas with high traffic intensity due to the height of its step.

430 **4. FUTURE PROSPECTS**

431 Regarding the different TEHDs reported in the literature, further testing in working
 432 conditions is considered necessary, since most of the current devices are presented
 433 without any real conditions testing. Moreover, there are very few numerical simulations
 434 of TEHDs that allow a more comprehensive study of the design parameters.

435 There are certain issues that are not covered by the existing TEHDs. Few
 436 investigations have taken into account how speed, traffic or vehicle weight affects the
 437 performance of a TEHD. A complete study of the combined influence of several design
 438 variables is considered necessary. Furthermore, a comparison of initial investment,
 439 maintenance cost, operating cost, energy savings and life span of TEHDs versus
 440 conventional speed bumps is considered necessary in order to establish the
 441 advantages and disadvantages of TEHDs.

442 Analyzing the undergoing research in this field and the amount of new devices
443 appearing continuously, the path to follow is on the one hand, the reduction of TEHDs'
444 dimensions in order to make them more affordable reducing installation and
445 maintenance cost, and on the other hand, the combination of different technologies in
446 one device with enhanced materials properties in order to maximize TEHDs' power
447 output.

448 **5. CONCLUSIONS**

449 Nowadays there is a strong focus in energy harvesting research, looking for new and
450 clean sources of energy for reducing natural resources consumption and greenhouse
451 gas emissions. Research in energy harvesting from vehicular traffic has an enormous
452 potential to achieve those objectives.

453 As a summary of all the issues discussed in point 4 the following findings can be
454 drawn:

- 455 • Hydraulic and mechanical TEHDs supply more average power per vehicle than
456 piezoelectric and electromagnetic technologies.
- 457 • Whereas for a mechanic or hydraulic TEHD, the vehicle weight and step height
458 decisively influence the power output, this is not the case for piezoelectric or
459 electromagnetic devices, where the influence is less significant. In these, the
460 vibration frequency of the device is the most important factor in the final power
461 output.
- 462 • Inadequate speeds also influence the efficiency, decreasing the pressure over
463 the TEHD and thus the power output.
- 464 • Traffic intensity and percentage of heavy vehicles are other important factors to
465 take into account.
- 466 • Mechanical technology has a lower initial investment. Nevertheless, these
467 devices are significantly larger than the others and for this reason cannot be
468 placed in areas with high traffic intensity due to the height of its step. However,
469 a TEHD with a larger initial investment and less power production per vehicle
470 placed in a high traffic intensity area can produce more total power per day, and
471 thus more energy savings and shorter payback periods.
- 472 • All this suggests the possibility of using a mixed TEHD capable of combining
473 different technologies resulting in a more efficient system.
- 474 • The intermittence of vehicular traffic as an energy source necessitates a
475 storage device. New batteries and ultra-capacitors have excellent storage
476 performances and their combination leads to more compact, lighter systems,
477 with a good relationship between power and energy. Furthermore this
478 combination enables the reduction of the required battery size, thus obtaining a
479 weight and cost reduction, and a longer life span.

480 Further investigation is needed to analyze the combined influence of design variables,
481 testing in real conditions and a comparison of initial investment, maintenance cost,
482 operating cost, energy savings and life span of TEHDs versus conventional speed
483 bumps.

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