

(19)



(11)

EP 1 390 246 B1

(12)

EUROPEAN PATENT SPECIFICATION

(45) Date of publication and mention of the grant of the patent:
15.08.2018 Bulletin 2018/33

(51) Int Cl.:
B61L 25/06 ^(2006.01) **B61L 23/00** ^(2006.01)
G08B 21/18 ^(2006.01)

(21) Application number: **02721848.6**

(86) International application number:
PCT/AU2002/000570

(22) Date of filing: **08.05.2002**

(87) International publication number:
WO 2002/090166 (14.11.2002 Gazette 2002/46)

(54) CONDITION MONITORING SYSTEM

ZUSTANDSÜBERWACHUNGSSYSTEM

SYSTEME DE SURVEILLANCE D'ETAT

(84) Designated Contracting States:
AT BE CH CY DE DK ES FI FR GR IE IT LI LU MC NL PT SE TR

- **HENRY, Manus**
 Headington,
 Oxfordshire OX3 7TR (GB)

(30) Priority: **08.05.2001 AU PR483201**
12.02.2002 GB 0203262

(74) Representative: **Maier, Daniel Oliver**
Siemens AG
Postfach 22 16 34
80506 München (DE)

(43) Date of publication of application:
25.02.2004 Bulletin 2004/09

(56) References cited:
WO-A1-97/33784 FR-A1- 2 745 543
FR-A1- 2 797 958 GB-A- 2 313 611
GB-A- 2 335 986 JP-A- 2000 112 777
NL-C2- 1 012 336

(73) Proprietors:
 • **Siemens Industry, Inc.**
Alpharetta, GA 30005 (US)
 • **Siemens Rail Automation Pty.Ltd.**
Melbourne VIC 3008 (AU)
 • **Siemens Rail Automation Limited**
Frimley,Camberley,
GU16 8QD (GB)
 • **Siemens Rail Automation Holdings Limited**
Frimley, Camberley, Surrey GU16 8QD (GB)

- **DATABASE WPI Week 200013, Derwent Publications Ltd., London, GB; AN 2000-139719, XP002974586 & JP 11 348 788 A (NIPPON SIGNAL CO LTD) 21 December 1999**
- **XILINX: "Xcell", xilinx.com , vol. 32, no. 2 1999, pages 1-64, Retrieved from the Internet: URL:http://www.xilinx.com/publications/archives/xcell/Xcell32.pdf [retrieved on 2018-01-31]**
- **Electronic Design: "Consider All The Factors When Selecting The Proper Inductive Proximity Sensor", , 30 April 2000 (2000-04-30), Retrieved from the Internet: URL:http://www.electronicdesign.com/components/consider-all-factors-when-selecting-proper-inductive-proximity-sensor [retrieved on 2018-03-01]**

(72) Inventors:
 • **BURTON, Colin**
Chippenham,
Wiltshire SN15 3TF (GB)
 • **BAKER, Stephen**
Mornington, Victoria 3931 (AU)
 • **WALSER, Jay**
Prospect, KY 40059 (US)

EP 1 390 246 B1

Note: Within nine months of the publication of the mention of the grant of the European patent in the European Patent Bulletin, any person may give notice to the European Patent Office of opposition to that patent, in accordance with the Implementing Regulations. Notice of opposition shall not be deemed to have been filed until the opposition fee has been paid. (Art. 99(1) European Patent Convention).

Description

[0001] The present invention relates to condition monitoring and in particular relates to a system for monitoring condition of a railways installation such as a points machine. The system includes a distributed array of sensors adapted to gather data regarding the status of elements of the installation with which the sensors are associated. The monitoring system may utilize advanced algorithms to process the data for a variety of purposes including predicting failure of equipment, developing efficient maintenance schedules and managing railway assets in general.

Although monitoring of a railway installation such as a points machine is known, prior art monitoring has been of a limited scope and typically has been limited to measurement of displacement to confirm that a switched rail has moved to a position sufficiently close to a stock rail to ensure safe operation. Prior art monitoring generally has been useful for detecting faults in infrastructure subsequent to failure of the monitored. Prior art monitoring systems are known from FR2797958 and FR2745543. Analysis of points machine faults reported over a five year period has shown that significant fault modes are not failures of the points machine itself (e.g. motor problems), but are due to problems with mechanical alignment of the monitored installation, including the track. The monitoring system of the present invention may provide reasonably comprehensive monitoring of this mechanical alignment. If a problem occurs, irrespective of the underlying cause (e.g. different types of obstruction, ballast movement, increased slide chair friction, mechanical looseness of various types), it should be visible via one or more sensors; conversely, if the relationship between all sensor signals is normal, this may be strong evidence that the mechanical alignment of the monitored installation is sound.

[0002] Consideration may be given as to how and more precisely when problems may manifest themselves. It is a well-established principle of validation that faults in a system are more readily diagnosed when it is undergoing stimulation, rather than when it rests in stasis. Of course the most obvious system stimulation occurs when the points are thrown, and naturally all points condition monitoring systems are active when this happens. Even so, a sparsely instrumented condition monitor which only observes, say, current, voltage and load force, is less likely to observe a loose stock rail than one which monitors stock rail movement directly.

[0003] An object of the present invention is to provide a tool for railways to prevent or at the very least to reduce interruptions to service caused by failures to equipment. Another object of the present invention is to provide a system which may monitor a plurality of measurements for the purpose of validating proper functioning of a points machine and its associated track. A further object is to provide means for enabling maintenance schedules and work to be planned and undertaken with greater efficien-

cy.

According to one aspect of the present invention there is provided a system for monitoring condition of a points machine, in accordance with appended claim 1. According to a further aspect of the present invention there is provided a method of monitoring condition of a points machine in accordance with appended claim 11.

[0004] Preferable features of the invention are defined in the appended dependent claims.

[0005] The condition monitoring system of the present invention includes a plurality of sensors for acquiring trackside data related to a plurality of different parameters and for logging key events. The sensors are connected or associated with elements of the installation (eg. points) being monitored. The sensors may be adapted to acquire data for several quantities or classes of parameters including force, power, current/voltage, spatial measurements including distance or displacement, electrical noise, temperature and state changes. In a specific embodiment sensors associated with the monitoring system may be adapted to measure one or more of: load force; switch blade position on each side thereof; motor voltage and current during operation; track and points machine temperature; lock and detection blade position on each side thereof; stock rail position on each side thereof; and points machine position (relative to a fixed point). The monitoring system may utilize information relating to at least two, and preferably at least three of the aforementioned parameters. Key events to be logged may include time stamping of points operation, opening and closing of case cover associated with a points machine, insertion and removal of a hand-crank, loss of supply current and passage or transit of a train.

[0006] Force measurement may be associated with movement of slide chairs, or may be indicative of an obstruction, clutch slip and/or snow obstruction. Sensors for performing force measurement may include a load cell or load pin and/or a strain gauge or gauges.

[0007] Sensors for performing distance or displacement measurements may include inductive analog proximity transducers. At the toe of each point there may be one or more proximity sensors for measuring closed blade gap, stock rail position and machine position. Sensors for monitoring the case cover and hand crank may include a micro switch. Temperature sensors may include thermistors or semiconductor devices. External radiation temperature may be measured directly. Motor current sensors may include Hall Effect instantaneous current transducers.

[0008] Measurements may be made and monitored in respect of electrical properties associated with a circuit controller, high resistance contacts in relays, high resistance contacts in hand crank cut-out and motor brushes/commutator.

[0009] The monitoring system may include an analog interface for interfacing the sensors to processing means. The analog interface may include signal conditioning and buffering circuits. The system may include a plurality of

analog to digital converters and a logic array for collecting data and forwarding to the processing means. The logic array may perform some preliminary processing. The processing means may include a suitably programmed digital computer such as a PC system.

[0010] The logic array may be provided in the form of a field programmable gate array (FPGA). The FPGA may continuously monitor the plurality of sensors and pass data to the PC system for processing and storage. The FPGA may collect data from the plurality of sensors at a relatively low speed in normal mode (eg 500Hz). Upon detecting an event such as a point movement or a train transit, the FPGA may switch to a relatively high speed mode (eg 2.5KHz) whilst focussing on a subset of the plurality of sensors. The subset of sensors selected as a focus for that high speed monitoring may be selected between one of two or more sub-sets having regard to the nature of the detected event.

[0011] The PC system may be provided on a single board (eg. PC104 module). The PC system may store a snapshot of the monitored system periodically, typically between every one and fifteen minutes, for example approximately every 4 minutes, and store this locally for use in on-line (ie, real time) trend analysis. The PC system may also archive data for later (off line) processing and analysis.

[0012] Off-line or on-line processing and analysis may be conveniently carried out by means of a condition monitoring and fault detection software toolkit.

[0013] Abnormal system operation may be detected by means of algorithms operating in distinct modes including modes such as those now described:

A threshold limit mode may detect when a monitored parameter exceeds a threshold value beyond which the points are considered to have failed. On reaching one or more of these threshold values an alarm condition may be triggered.

[0014] A rate of change mode may give consideration to any parameter that is changing in such a way that extrapolation would show that it will exceed a threshold value in a given time period.

[0015] A signature mode may monitor signature of each parameter over time or events. The signature may change over time. A change in the signature at a rate greater than that expected may be utilized to provide an indication of a potential failure.

[0016] A behaviour mode may make use of a series of models of known behaviours. The models may be generated by means of a test site for simulating a range of failures. Signatures of the behaviour may be modelled and used to predict such failures or as a tool to assist diagnosis of failures.

[0017] A correlation mode may compare changes in status of parameters from different reference planes. The changes in parameters may be expected to move in unison, or other defined relationship, and any departure from this may be interpreted to indicate a possible failure. The correlation mode may provide an indication of changes

to the mechanical alignment of the monitored installation.

[0018] By monitoring parameters before and after maintenance it may be possible to gauge effectiveness of the maintenance and to confirm that the maintenance was necessary. It may also be possible to determine when to perform maintenance. As the monitoring system is capable of returning numerical data, the system may also act as a measurement tool to assist in maintenance functions.

[0019] Situations in which detailed observation and analysis of points behaviour can provide additional diagnostic data include post-movement relaxation and train transits.

[0020] It has been observed that in the aftermath of a points machine movement, there is a gradual change in various positions and load force, as the machine settles down over the following ten minutes or so. The extent of such relaxation may give an indication of how firmly the machine and the points are secured. Any looseness may show itself as a much greater shift in load force or position. Thresholds may be established for permitted levels of relaxation which, if exceeded, can trigger alarms requesting maintenance action.

[0021] If the points machine and its associated track are viewed essentially as a mechanical system where each of the parts must stay in correct alignment for proper functioning, then it is found that the transit of a train, with the corresponding huge injection of mechanical energy into the system, provides a valuable opportunity for testing fastness of the mechanical alignment. For example data which follows train movements may be recorded as they occur up to ten minutes after a points machine movement. The rattling and sometimes the shift in value caused by the train are clearly superimposed upon the post-movement relaxation trends described above. A contrast can be drawn between a site where there is little or no shift in signal values before and after a train event, and one where relatively large and permanent shifts in value may occur.

[0022] The behaviour of the points machine and its associated track during a train passage may provide valuable extra information on how securely the mechanical system is fixed. It is a straightforward matter to set alarm limits on the extent of such shifts, or the standard deviation (extent of rattle) of the signals during a train transit. Trending may also be deployed to see how such parameters vary with time. An important issue is deciding at what level thresholds should be set.

[0023] Stored reference data regarding selected parameters of the plurality of parameters may be updated with detected changes in those parameters (when those changes are within predetermined acceptably limits), such as are for example typical of normal wear or aging. The updated reference data may then be employed as a reference point for monitoring whether subsequent changes or rate of change of those parameters are indicative of the occurrence for a heightened risk of a malfunction.

[0024] The monitoring system may feature use of fixed thresholds or stored reference data for one or some of the parameters, e.g. parameters such as closure gap distance which are potentially safety critical.

[0025] The processing means may include a digital computer programmed with condition monitoring and fault detection software. The software may be adapted to monitor behavioural trends. For example it may monitor trends which occur within a defined range of parameters and may provide that changes represented by those trends are used to create an updated reference point relative to which the system may then monitor for any higher rate of change or change of absolute level which would indicate the occurrence of or a heightened risk of a malfunction.

[0026] The system may include an interface to a communications network such as the internet. At least some processing modes as outlined above may be performed on-line via the PC system to provide trend analysis. The numerical data and on-line analysis may be available via the communications network to allow an operator to 'see' what is happening at the points and make value judgements based on that information.

[0027] The monitoring system may provide information through its communication interface and off line reports to the operator to diagnose an event. By providing real time physical data the system may serve as a valuable maintenance tool by providing service adjustment information from the monitored equipment.

[0028] Moreover, by utilizing analysis tools as described herein the monitoring system may predict possible failure and/or provide suitable warnings of impending failure. A capacity to predict a future condition of the monitored equipment may facilitate determination of when maintenance needs to be performed as well as the type of maintenance to be performed.

[0029] An exemplary embodiment of the present invention is described below with reference to the accompanying drawings in which:-

Fig. 1 shows a block diagram of a condition monitoring system according to the present invention;

Fig. 2 shows one embodiment of the condition monitoring system of Fig. 1;

Fig. 3 shows the disposition of sensors relative to a points machine; and

Fig. 4 shows a table of the sensors in Fig. 3.

[0030] Referring to Fig. 1, a plurality of sensors. S_1 to S_N is associated with elements of a railway infrastructure. Sensors S_1 to S_N are adapted to measure plural quantities or classes of parameters including force, displacement, current, voltage, temperature, electrical noise, state changes etc... Sensors S_1 to S_N are connected to analog interface module 10. Interface module 10 includes signal conditioning and buffering circuits. The outputs of analog interface module 10 are connected to Analog to Digital (ADC) converter module 11. ADC module 11 is

adapted to convert analog data gathered by sensors S_1 to S_N to a digital domain. Digital data from ADC module 11 is passed to processing module 12.

[0031] Processing module 12 may include a logical array such as an FPGA for performing preliminary processing of data. Processing module 12 may include a digital computer such as a suitably programmed PC system for performing on-line (ie real time) processing of data. If appropriate, the processing module may be partitioned so that preliminary processing may take place within an FPGA in one location (for example within the railway equipment), while further processing takes place remotely in a separate processor, with data communication taking place over a suitable link between the FPGA and processing module. In one instantiation, a single processing module may be linked up with several FPGA modules, each of which is associated with a separate piece of railway equipment.

[0032] The system includes a storage module 13 for archiving data. Archived data may be processed off-line via suitable analysis software. The monitoring system may be connected to a local or wide area network via network interface module 14. The system may also include a display/keyboard module 15 for providing a user interface to the monitoring system. Alternatively, a laptop or palmtop device may communicate with the monitoring system via its network capability, to act as a local terminal.

[0033] Fig. 2 shows an exemplary embodiment of the monitoring system including an array of sensors 20. The array of sensors 20 monitors a variety of parameters and parameter types including displacement, current, voltage, temperature and state changes. Optionally duplicate sensors may be provided for at least some of the parameters, especially any sensors that are of a less reliable type.

[0034] The disposition of sensors relative to a points machine is shown in Fig. 3. A table of the sensors in Fig. 3 is set forth in Fig. 4. Analog signals from sensors 20 are connected to analog interface card 21 for providing signal conditioning and buffering of the analog signals. The conditioned and buffered signals are passed to FPGA card 22. FPGA card 22 includes a plurality of ADCs, local RAM as well as a Xilinx 4085 chip FPGA for controlling and gathering data from the ADC's. Each ADC may include a sigma delta analog to digital converter. The local RAM may include 256Kx16 SRAM. The FPGA averages the data and stores it in the local RAM making it available to PC card 23 upon request. The FPGA is a resource of approximately 85,000 logic gates, which can be dynamically configured and connected under software control. Functionality within the FPGA is determined by a configuration file, which must be loaded before the FPGA can perform its desired functions.

[0035] The configuration bitstream which defines the functionality of the FPGA can be loaded under the control of a host, into the FPGA. The bitstream for the FPGA originates from a "HandelC" source file. This describes

the desired functionality using a C - like syntax, but it is compiled into a list of hardware requirements by the HandelC compiler, rather than processor instructions. The netlist which results from this compilation is then processed by the Xilinx toolset, into a bitstream suitable for downloading into the FPGA by a host.

[0036] The FPGA continuously monitors sensor array 20 and passes data each second to PC card 23 for further action. The FPGA carries out the following functions in the current embodiment:

It communicates to the PC processor over a PC104 bus, updating the PC on the status of the points machine, accepting and responding to commands from the PC, and sending data to the PC on request.

[0037] It controls the buffering of data in the local RAM memory until the PC is ready to receive it, thus relieving the PC of responsibility for time-critical operations.

[0038] It controls analog-to-digital converters (ADCs), these being Analog Devices' AD7731s. These are so-called sigma-delta converters with a high degree of programmability. For each ADC, any one of up to 3 input channels can be monitored; the sampling rate, input gain (e.g. multiply the input signal by 1, 2, 4, 8 ...), and output word precision (e.g. 16 or 24 bits) can all be configured. In the current embodiment, the ADCs are used to monitor a total of 18 input channels under FPGA control, each having up to 3 distinct inputs.

[0039] In a default (background) mode of operation the FPGA monitors all 18 channels in turn. The ADCs are continuously reprogrammed in parallel to read each of their 3 input channels in turn. This results in a sampling rate of approximately 500Hz on all channels. The FPGA carries out some simple signal conditioning, and saves the resulting data in a compact form so that the PC can read the channel data at a rate of only 1Hz.

[0040] Each time new data is read, the FPGA checks to see whether a new 'event' has begun, such as a points machine movement including post movement relaxation or a train passage or transit. If so, the FPGA indicates to the PC that a new event has begun and reprograms the ADCs to carry out a different data acquisition scheme. For example, during a points machine movement only five channels are sampled, but at 2.5kHz per channel. The data are stored in the local RAM memory for transmission to the PC once the event is completed. If desirable, further data processing (e.g. data compaction) can be carried out to reduce the volume of data sent to the PC. On completion of the event, a normal background pattern of data acquisition is resumed.

[0041] Upon detecting an event such as point movement or passage of a train the FPGA switches into a high speed data acquisition mode for a subset of the sensor array. It passes all of its data to PC card 23 for processing and storage. PC card 23 includes a PC104 Form factor PC. This is a complete PC system comprising memory, I/O, etc, in a footprint of ~90mm x 96mm and is a commercially produced product. The operating system used is VXWorks from Windriver. The "PC104 expansion bus"

is in effect a PC ISA bus in a different form factor, allowing vertical "stacking" of expansion boards, rather than conventional motherboard "slots".

[0042] PC card 23 stores samples of data every 4 minutes in Local Storage for use in an on line trend analysis. Data is also archived on flash disk 24 for off-line processing and analysis.

[0043] The system includes network access module 25 for interacting with a wide area network such as the internet. Console access module 26 including a monitor and a keyboard provides an interface to a human operator.

[0044] A variety of analysis techniques may be used to detect significant changes in equipment behaviour, including the following:

THRESHOLD LIMIT MODE

[0045] In this mode each of the parameters may have a threshold limit beyond which the points are considered to have failed. On reaching one or more of these values an alarm may be given.

RATE OF CHANGE MODE

[0046] In this mode consideration may be given to any parameter that is changing in such a way that extrapolation would show it exceeding a threshold limit in a given time period.

DEVIATION FROM EXPECTED BEHAVIOUR MODE

[0047] All parameters generate a signature over a period of time or events. This signature may change over time. A change in this signature at a rate greater than expected may indicate a possible failure.

BEHAVIOUR MODEL MODE

[0048] Using a test site a series of known behaviours and results from failures may be simulated. This signature of these behaviours may be modelled and used to either predict the failures or be used as a tool to assist in the diagnosis of failures.

CORRELATION OF PARAMETERS MODE

[0049] As a number of sensors are applied to the points, some are capable of showing the same changes in status but from different reference planes. These parameters may be expected to move in unison and any departure from this may indicate a possible failure.

[0050] One possible means of carrying out such data analysis, whether offline or online is by means of condition monitoring and fault detection (CMFD) software designed to have as one of its main objectives the detection of abnormal operation and subsequent diagnosis of identification of contributing factors leading to abnormal op-

eration. The CMFD software may operate with a real-time control engine to provide on-line status information about the monitored operation. Two of the technologies that the CMFD software may provide include data compression and modelling algorithms.

[0051] One data compression algorithm is Principal Component Analysis (PCA). PCA examines many variables and identifies key correlations between them. It then generates a much smaller set of variables, called 'principal components', which retain the majority of the information contained in the original measurements. The relationship between new measurements and the generated components can be monitored to detect a change in the underlying relationships that govern the railway equipment.

[0052] A second data compression algorithm is called Partial Least Squares (PLS), and uses Least Squares (LS) type modelling to identify a relationship between inputs and outputs. It too compresses the variables, but unlike PCA it differentiates between inputs and outputs. Internal variables, known as 'latent variables', are modelled using a variation of LS modelling, and can be monitored in order to detect changes in operation. Cross validation may be included for both these algorithms to aid selection of components and latent variables.

[0053] In real-time operation, for both PCA and PLS, the CMFD software may be employed to fill-in for missing data to allow process condition monitoring to continue even if individual signals are lost. Traditional Model-Based Statistical Process Control indicators such as the T^2 and Q statistics may also be included. These may be derived directly from the PCA and PLS engines, and are established quality measures. Two characterisation engines may be included that allow the user to detect abnormal process operation, namely Elliptical Density Estimation (EDE) and Kernel Density Estimation (KDE). Both EDE and KDE may use historical data from the process to form a definition of 'normal' process operation. These algorithms may be used in conjunction with PCA or PLS to further enhance the capability of the CMFD software to detect abnormal operation.

[0054] Multiple condition monitors may be run side-by-side in real-time, or a single condition monitor may support a number of different model sets. In this latter configuration, a degree of automatic process classification may be possible based on the PCA/PLS models and the analysis of clusters.

[0055] The processing analysis may be adapted for detecting abnormal system operation as well as subsequent diagnosis and identification of contributing factors leading to abnormal operation.

Because parameters are monitored before and after maintenance the analysis may provide an indication of the effectiveness of the maintenance and/or whether the maintenance was in fact necessary. The analysis may also determine when maintenance is to be performed. Maintenance functions may be assisted because the monitoring system is capable of returning numerical data

and may thereby act as a measurement tool.

Because the system may provide data through its web interface continuously, it is possible to "see" what is happening at the points and to make value judgements based on the information. Through the network interface and off-line reports the monitoring system may provide information to the maintainer to diagnose an event. By providing real time physical data the system may be able to give the maintainer adjustment information for the installation. By using all the analysis tools described above it may be possible for the system to predict possible failure and to provide a suitable pre-warning. As the system includes an ability to predict a possible future condition of the equipment it is possible to determine when maintenance will be needed and what type of maintenance is to be performed.

It is to be understood that the invention described hereinabove is susceptible to variations, modifications and/or additions other than those specifically described and that the invention includes all such variations, modifications and/or additions which fall within the scope of the above description.

25 Claims

1. A system for monitoring condition of a points machine, said system including: a plurality of sensors (S1,...,SN; 20) associable with elements of said points machine for monitoring parameters indicative of operating capability of said points machine; and means for processing (12) said monitored parameters to determine whether said parameters are changing relative to reference values and to determine whether the changes are indicative of an increased risk of a malfunction in said points machine; wherein said sensors (S1,...,SN; 20) are adapted to monitor at least one or more of lock and detection blade position on each side thereof, stock rail position on each side thereof, and points machine position relative to a fixed point,

characterized in that

the monitoring system further includes an analog interface (10, 21) for interfacing the sensors (S1,...,SN; 20) to the processing means (12), and a plurality of analog to digital converters (11) and a logic array for collecting data and forwarding to the processing means (12), wherein the logic array is a field programmable gate array, FPGA (22), and the FPGA (22) is adapted to collect data from the plurality of sensors (S1,...,SN; 20) at a relatively low speed in normal mode, whereas upon detecting an event such as a point movement or a train transit, the FPGA (22) is adapted to switch to a relatively high speed data acquisition mode for a subset of the plurality of sensors (S1,...,SN; 20), and the monitoring system is adapted to trigger an alarm condition when a monitored parameter reaches or exceeds one or more

- threshold values.
2. A system according to Claim 1, wherein the changes in said parameters include a rate of change of one or more of said parameters. 5
 3. A system according to Claim 1 or 2, wherein said monitored parameters are used to update said reference values within predetermined limits. 10
 4. A system according to Claim 1,2 or 3, wherein said parameters include two or more of force, power, distance or displacement, temperature, state changes and electrical properties including resistance, current, voltage and electrical noise. 15
 5. A system according to Claim 1 wherein said sensors (S1,...,SN; 20) are additionally adapted to monitor at least one or more of load force, switch blade position on each side thereof, motor voltage and current during operation, and track and points machine temperatures. 20
 6. A system according to Claim 5 wherein a sensor (S1,...,SN; 20) for measuring load force is associated with slide chairs in said points machine. 25
 7. A system according to Claim 5 or 6 wherein a sensor (S1,...,SN; 20) for measuring voltage and/or current is associated with an electric motor in said points machine. 30
 8. A system according to any one of the preceding Claims including the means for interfacing said sensors (S1,...,SN; 20) to said processing means (12), wherein said interfacing means (10, 21) include signal conditioning and buffering circuits. 35
 9. A system according to any one of the preceding Claims wherein said processing means (12) includes a digital computer (23) programmed with condition monitoring and fault detection software. 40
 10. A system according to Claim 9 wherein said software includes at least one algorithm operating in one or more of a threshold limit mode, a rate of change mode, a deviation from expected behaviour mode, a behaviour model mode and a correlation of parameters mode. 45
 11. A method of monitoring condition of a points machine said method including the steps of: monitoring with a plurality of sensors (S1,...,SN; 20) at least one or more of lock and detection blade position on each side thereof, stock rail position on each side thereof, and points machine position relative to a fixed point; **characterized in that** further including interfacing the sensors (S1,...,SN; 20) to processing means (12), and a plurality of analog to digital converters (11) and a logic array for collecting data and forwarding to the processing means (12), wherein the logic array is a field programmable gate array, FPGA (22), and the FPGA (22) collects data from the plurality of sensors (S1,...,SN; 20) at a relatively low speed in normal mode, whereas upon detecting an event such as a point movement or a train transit, the FPGA (22) switches to a relatively high speed data acquisition mode for a subset of the plurality of sensors, and processing the monitored parameters to determine whether said parameters are changing relative to reference values and to determine whether the changes are indicative of an increased risk of a malfunction in said points machine, and wherein on reaching one or more of the reference values an alarm condition is triggered. 50
 12. A method according to Claim 11, wherein the changes in said parameters include a rate of change of one or more of said parameters. 55
 13. A method according to Claim 11 or 12, wherein said monitored parameters are used to update said reference values within predetermined limits.
 14. A method according to Claim 11, 12 or 13, wherein said parameters include two or more of force, power, distance or displacement, temperature, state changes and electrical properties including resistance, current, voltage and electrical noise.
 15. A method according to Claim 11 wherein said sensors (S1,...,SN; 20) are additionally adapted to monitor at least one or more of load force, switch blade position on each side thereof, motor voltage and current during operation, and track and points machine temperatures.
 16. A method according to Claim 15 wherein a sensor (S1,...,SN; 20) for measuring load force is associated with slide chairs in said points machine.
 17. A method according to Claim 15 or 16 wherein a sensor (S1,...,SN; 20) for measuring voltage and/or current is associated with an electric motor in said points machine.
 18. A method according to any one of Claims 11 to 17 wherein the interfacing of said sensors (S1,...,SN; 20) to the processing means (12) is further achieved by means of signal conditioning and buffering circuits.
 19. A method according to any one of Claims 11 to 18 wherein said processing is performed by means of a digital computer (23) programmed with condition

monitoring and fault detection software.

20. A method according to Claim 19 wherein said software includes at least one algorithm operating in one or more of a threshold limit mode, a rate of change mode, a deviation from expected behaviour mode, a behaviour model mode and a correlation of parameters mode.

Patentansprüche

1. System zum Überwachen des Zustands eines Weichenantriebs, wobei dieses System aufweist: mehrere Sensoren (S1, ..., SN; 20), die Elementen des Weichenantriebs zum Überwachen von Parametern zuordenbar sind, die für die Betriebsfähigkeit des Weichenantriebs indikativ sind; und Mittel zum Verarbeiten (12) der überwachten Parameter, um zu bestimmen, ob sich die Parameter in Bezug auf Referenzwerte ändern, und zu bestimmen, ob die Änderungen für ein erhöhtes Risiko einer Funktionsstörung in dem Weichenantrieb indikativ sind; wobei die Sensoren (S1, ..., SN; 20) dafür ausgelegt sind, wenigstens eine oder mehrere von Position von Verriegelungs- und Detektionszunge auf jeder Seite derselben, Position der Backenschiene auf jeder Seite derselben und Weichenantriebsposition in Bezug auf einen festen Punkt zu überwachen, **dadurch gekennzeichnet, dass** das Überwachungssystem ferner eine Analogschnittstelle (10, 21) zum Anschließen der Sensoren (S1, ..., SN; 20) an die Verarbeitungsmittel (12) und mehrere Analog-Digital-Umsetzer (11) und eine Logikanordnung zum Sammeln von Daten und Weiterleiten an die Verarbeitungsmittel (12) aufweist, wobei die Logikanordnung ein feldprogrammierbares Gate-Array, FPGA (22), ist und das FPGA (22) dafür ausgelegt ist, in einer normalen Betriebsart Daten von den mehreren Sensoren (S1, ..., SN; 20) mit einer relativ niedrigen Geschwindigkeit zu sammeln, während beim Detektieren eines Ereignisses, wie etwa einer Weichenbewegung oder einer Zugdurchfahrt, das FPGA (22) dafür ausgelegt ist, für eine Teilmenge der mehreren Sensoren (S1, ..., SN; 20) zu einer Betriebsart der Datenerfassung mit relativ hoher Geschwindigkeit umzuschalten, und das Überwachungssystem dafür ausgelegt ist, einen Alarmzustand auszulösen, wenn ein überwachter Parameter einen oder mehrere Schwellenwerte erreicht oder überschreitet.
2. System nach Anspruch 1, wobei die Änderungen in den Parametern eine Änderungsgeschwindigkeit eines oder mehrerer der Parameter aufweisen.
3. System nach Anspruch 1 oder 2, wobei die überwachten Parameter verwendet werden, um die Re-

ferenzwerte innerhalb vorbestimmter Grenzen zu aktualisieren.

4. System nach Anspruch 1, 2 oder 3, wobei die Parameter zwei oder mehr von Kraft, Leistung, Abstand oder Verschiebung, Temperatur, Zustandsänderungen und elektrischen Eigenschaften, darunter Widerstand, Stromstärke, Spannung und elektrische Störungen, beinhalten.
5. System nach Anspruch 1, wobei die Sensoren (S1, ..., SN; 20) zusätzlich dafür ausgelegt sind, wenigstens eines oder mehrere von Belastungskraft, Position der Weichenzunge auf jeder Seite derselben, Motorspannung und -strom während des Betriebs und Gleis- und Weichenantriebs-Temperaturen zu überwachen.
6. System nach Anspruch 5, wobei ein Sensor (S1, ..., SN; 20) zum Messen der Belastungskraft Gleitstühlen in dem Weichenantrieb zugeordnet ist.
7. System nach Anspruch 5 oder 6, wobei ein Sensor (S1, ..., SN; 20) zum Messen von Spannung und/oder Stromstärke einem Elektromotor in dem Weichenantrieb zugeordnet ist.
8. System nach einem der vorhergehenden Ansprüche, welches die Mittel zum Anschließen der Sensoren (S1, ..., SN; 20) an die Verarbeitungsmittel (12) aufweist, wobei diese Anschlussmittel (10, 21) Signalaufbereitungs- und Pufferschaltungen aufweisen.
9. System nach einem der vorhergehenden Ansprüche, wobei die Verarbeitungsmittel (12) einen Digitalrechner (23) aufweisen, der mit Zustandsüberwachungs- und Fehlerdetektions-Software programmiert ist.
10. System nach Anspruch 9, wobei die Software wenigstens einen Algorithmus umfasst, der in einer oder mehreren von einer Schwellenwertgrenzen-Betriebsart, einer Änderungsgeschwindigkeits-Betriebsart, einer Betriebsart der Abweichung vom erwarteten Verhalten, einer Verhaltensmodell-Betriebsart und einer Betriebsart der Korrelation von Parametern arbeitet.
11. Verfahren zum Überwachen des Zustands eines Weichenantriebs, wobei das Verfahren die Schritte umfasst:
Überwachen, mit mehreren Sensoren (S1, ..., SN; 20), wenigstens einer oder mehrerer von Position von Verriegelungs- und Detektionszunge auf jeder Seite derselben, Position der Backenschiene auf jeder Seite derselben und Wei-

chenantriebsposition in Bezug auf einen festen Punkt;

dadurch gekennzeichnet, dass

es ferner das Anschließen der Sensoren (S1, ..., SN; 20) an Verarbeitungsmittel (12) und mehrere Analog-Digital-Umsetzer (11) und eine Logikanordnung zum Sammeln von Daten und Weiterleiten an die Verarbeitungsmittel (12) umfasst, wobei die Logikanordnung ein feldprogrammierbares Gate-Array, FPGA (22), ist und das FPGA (22) in einer normalen Betriebsart Daten von den mehreren Sensoren (S1, ..., SN; 20) mit einer relativ niedrigen Geschwindigkeit sammelt, während beim Detektieren eines Ereignisses, wie etwa einer Weichenbewegung oder einer Zugdurchfahrt, das FPGA (22) für eine Teilmenge der mehreren Sensoren zu einer Betriebsart der Datenerfassung mit relativ hoher Geschwindigkeit umschaltet, und das Verarbeiten der überwachten Parameter, um zu bestimmen, ob sich die Parameter in Bezug auf Referenzwerte ändern, und zu bestimmen, ob die Änderungen für ein erhöhtes Risiko einer Funktionsstörung in dem Weichenantrieb indikativ sind, und wobei beim Erreichen eines oder mehrerer der Referenzwerte ein Alarmzustand ausgelöst wird.

12. Verfahren nach Anspruch 11, wobei die Änderungen in den Parametern eine Änderungsgeschwindigkeit eines oder mehrerer der Parameter aufweisen.
13. Verfahren nach Anspruch 11 oder 12, wobei die überwachten Parameter verwendet werden, um die Referenzwerte innerhalb vorbestimmter Grenzen zu aktualisieren.
14. Verfahren nach Anspruch 11, 12 oder 13, wobei die Parameter zwei oder mehr von Kraft, Leistung, Abstand oder Verschiebung, Temperatur, Zustandsänderungen und elektrischen Eigenschaften, darunter Widerstand, Stromstärke, Spannung und elektrische Störungen, beinhalten.
15. Verfahren nach Anspruch 11, wobei die Sensoren (S1, ..., SN; 20) zusätzlich dafür ausgelegt sind, wenigstens eines oder mehrere von Belastungskraft, Position der Weichenzunge auf jeder Seite derselben, Motorspannung und -strom während des Betriebs und Gleis- und Weichenantriebs-Temperaturen zu überwachen.
16. Verfahren nach Anspruch 15, wobei ein Sensor (S1, ..., SN; 20) zum Messen der Belastungskraft Gleitstühlen in dem Weichenantrieb zugeordnet ist.
17. Verfahren nach Anspruch 15 oder 16, wobei ein Sensor (S1, ..., SN; 20) zum Messen von Spannung

und/oder Stromstärke einem Elektromotor in dem Weichenantrieb zugeordnet ist.

18. Verfahren nach einem der Ansprüche 11 bis 17, wobei das Anschließen der Sensoren (S1, ..., SN; 20) an die Verarbeitungsmittel (12) ferner mithilfe von Signalaufbereitungs- und Pufferschaltungen bewerkstelligt wird.
19. Verfahren nach einem der Ansprüche 11 bis 18, wobei die Verarbeitung mittels eines Digitalrechners (23) durchgeführt wird, der mit Zustandsüberwachungs- und Fehlerdetektions-Software programmiert ist.
20. Verfahren nach Anspruch 19, wobei die Software wenigstens einen Algorithmus umfasst, der in einer oder mehreren von einer Schwellenwertgrenzen-Betriebsart, einer Änderungsgeschwindigkeits-Betriebsart, einer Betriebsart der Abweichung vom erwarteten Verhalten, einer Verhaltensmodell-Betriebsart und einer Betriebsart der Korrelation von Parametern arbeitet.

Revendications

1. Système de surveillance de l'état d'un mécanisme de manoeuvre d'aiguillage, ledit système comprenant : une pluralité de capteurs (S1, ..., SN ; 20) associables à des éléments dudit mécanisme de manoeuvre d'aiguillage en vue de surveiller des paramètres indicatifs de la capacité opérationnelle dudit mécanisme de manoeuvre d'aiguillage, et un moyen de traitement (12) desdits paramètres surveillés en vue de déterminer si lesdits paramètres changent par rapport à des valeurs de référence, et de déterminer si les changements sont indicatifs d'un risque accru de mauvais fonctionnement dudit mécanisme de manoeuvre d'aiguillage, étant entendu que lesdits capteurs (S1, ..., SN ; 20) sont adaptés en vue de surveiller au moins une ou plusieurs positions de lames de verrouillage et de détection de chaque côté de celles-ci, la position des contre-aiguilles de chaque côté de celles-ci et la position du mécanisme de manoeuvre d'aiguillage par rapport à un point fixe, **caractérisé en ce que:** le système de surveillance comprend par ailleurs une interface analogique (10, 21) pour interfacer les capteurs (S1, ..., SN ; 20) au moyen de traitement (12), et une pluralité de convertisseurs analogique-numérique (11) et un réseau logique servant à collecter des données et à les relayer au moyen de traitement (12), étant entendu que le réseau logique est un réseau de portes programmables par l'utilisateur (FPGA) (22) et que le FPGA (22) est adapté en vue de collecter des données provenant de la plu-

- ralité de capteurs (S1, ..., SN ; 20) à une vitesse relativement basse en mode normal tandis que, lors de la détection d'un événement tel que le mouvement d'une pointe d'aiguille ou le passage d'un train, le FPGA (22) est adapté en vue de basculer dans un mode d'acquisition de données à vitesse relativement élevée pour un sous-ensemble de la pluralité de capteurs (S1, ..., SN ; 20), et que le système de surveillance est adapté pour déclencher un état d'alerte quand un paramètre surveillé atteint ou dépasse une ou plusieurs valeurs seuils.
2. Système selon la revendication 1, étant entendu que les changements desdits paramètres consistent en une vitesse de changement d'un ou de plusieurs desdits paramètres.
 3. Système selon la revendication 1 ou 2, étant entendu que lesdits paramètres surveillés sont utilisés pour actualiser lesdites valeurs de référence dans des limites prédéterminées.
 4. Système selon la revendication 1, 2 ou 3, étant entendu que lesdits paramètres comprennent deux ou plusieurs paramètres parmi la force, la puissance, la distance ou le déplacement, la température, les changements d'état et des propriétés électriques dont la résistance, l'intensité du courant, la tension et le bruit électrique.
 5. Système selon la revendication 1 étant entendu que lesdits capteurs (S1, ..., SN ; 20) sont de plus adaptés en vue de surveiller au moins un ou plusieurs paramètres parmi la force de charge, la position des lames d'aiguille de chaque côté de celles-ci, la tension et l'intensité du courant d'un moteur en service et les températures des voies et des mécanismes de manoeuvre d'aiguillage.
 6. Système selon la revendication 5 étant entendu qu'un capteur (S1, ..., SN ; 20) servant à mesurer la force de charge est associé à des coussinets de glissement dudit mécanisme de manoeuvre d'aiguillage.
 7. Système selon la revendication 5 ou 6 étant entendu qu'un capteur (S1, ..., SN ; 20) servant à mesurer la tension et/ou l'intensité du courant est associé à un moteur électrique dudit mécanisme de manoeuvre d'aiguillage.
 8. Système selon l'une quelconque des revendications précédentes, comprenant les moyens servant à interfacier lesdits capteurs (S1, ..., SN ; 20) audit moyen de traitement (12), étant entendu que lesdits moyens d'interfaçage (10, 21) comprennent des circuits de mise en forme et en tampon de signaux.
 9. Système selon l'une quelconque des revendications précédentes étant entendu que ledit moyen de traitement (12) consiste en un calculateur numérique (23) programmé avec un logiciel de surveillance d'état et de détection de défauts.
 10. Système selon la revendication 9 étant entendu que ledit logiciel comprend au moins un algorithme fonctionnant dans un ou plusieurs modes parmi un mode à limite seuil, un mode à vitesse de changement, un mode à écart par rapport au comportement attendu, un mode à modèle de comportement et un mode à corrélation de paramètres.
 11. Procédé de surveillance d'état d'un mécanisme de manoeuvre d'aiguillage, ledit procédé comprenant les étapes consistant : à surveiller, avec une pluralité de capteurs (S1, ..., SN ; 20), au moins au moins une ou plusieurs positions de lames de verrouillage et de détection de chaque côté de celles-ci, la position des contre-aiguilles de chaque côté de celles-ci et la position du mécanisme de manoeuvre d'aiguillage par rapport à un point fixe,

caractérisé en ce que:

il comprend par ailleurs l'interfaçage des capteurs (S1, ..., SN ; 20) au moyen de traitement (12), et une pluralité de convertisseurs analogique-numérique (11) et un réseau logique servant à collecter des données et à les relayer au moyen de traitement (12), étant entendu que le réseau logique est un réseau de portes programmables par l'utilisateur (FPGA) (22) et que le FPGA (22) collecte des données provenant de la pluralité de capteurs (S1, ..., SN ; 20) à une vitesse relativement basse en mode normal tandis que, lors de la détection d'un événement tel que le mouvement d'une pointe d'aiguille ou le passage d'un train, le FPGA (22) bascule dans un mode d'acquisition de données à vitesse relativement élevée pour un sous-ensemble de la pluralité de capteurs, et le traitement des paramètres surveillés en vue de déterminer si lesdits paramètres changent par rapport à des valeurs de référence, et de déterminer si les changements sont indicatifs d'un risque accru de mauvais fonctionnement dudit mécanisme de manoeuvre d'aiguillage, et étant entendu que, lorsqu'une ou plusieurs des valeurs de référence sont atteintes, un état d'alerte est déclenché.
 12. Procédé selon la revendication 11, étant entendu que les changements desdits paramètres consistent en une vitesse de changement d'un ou de plusieurs desdits paramètres.
 13. Procédé selon la revendication 11 ou 12, étant en-

tendu que lesdits paramètres surveillés sont utilisés pour actualiser lesdites valeurs de référence dans des limites prédéterminées.

14. Procédé selon la revendication 11, 12 ou 13, étant entendu que lesdits paramètres comprennent deux ou plusieurs paramètres parmi la force, la puissance, la distance ou le déplacement, la température, les changements d'état et des propriétés électriques dont la résistance, l'intensité du courant, la tension et le bruit électrique. 5
10
15. Procédé selon la revendication 11 étant entendu que lesdits capteurs (S1, ..., SN ; 20) sont de plus adaptés en vue de surveiller au moins un ou plusieurs paramètres parmi la force de charge, la position des lames d'aiguille de chaque côté de celles-ci, la tension et l'intensité du courant d'un moteur en service et les températures des voies et du mécanisme de manoeuvre d'aiguillage. 15
20
16. Procédé selon la revendication 15 étant entendu qu'un capteur (S1, ..., SN ; 20) servant à mesurer la force de charge est associé à des coussinets de glissement dudit mécanisme de manoeuvre d'aiguillage. 25
17. Procédé selon la revendication 15 ou 16 étant entendu qu'un capteur (S1, ..., SN ; 20) servant à mesurer la tension et/ou l'intensité du courant est associé à un moteur électrique dudit mécanisme de manoeuvre d'aiguillage. 30
18. Procédé selon l'une quelconque des revendications 11 à 17 étant entendu que l'interfaçage desdits capteurs (S1, ..., SN ; 20) au moyen de traitement (12) est par ailleurs réalisé au moyen de circuits de mise en forme et en tampon de signaux. 35
19. Procédé selon l'une quelconque des revendications 11 à 18 étant entendu que ledit traitement est exécuté au moyen d'un calculateur numérique (23) programmé avec un logiciel de surveillance d'état et de détection de défauts. 40
45
20. Procédé selon la revendication 19 étant entendu que ledit logiciel comprend au moins un algorithme fonctionnant dans un ou plusieurs modes parmi un mode à limite seuil, un mode à vitesse de changement, un mode à écart par rapport au comportement attendu, un mode à modèle de comportement et un mode à corrélation de paramètres. 50

55

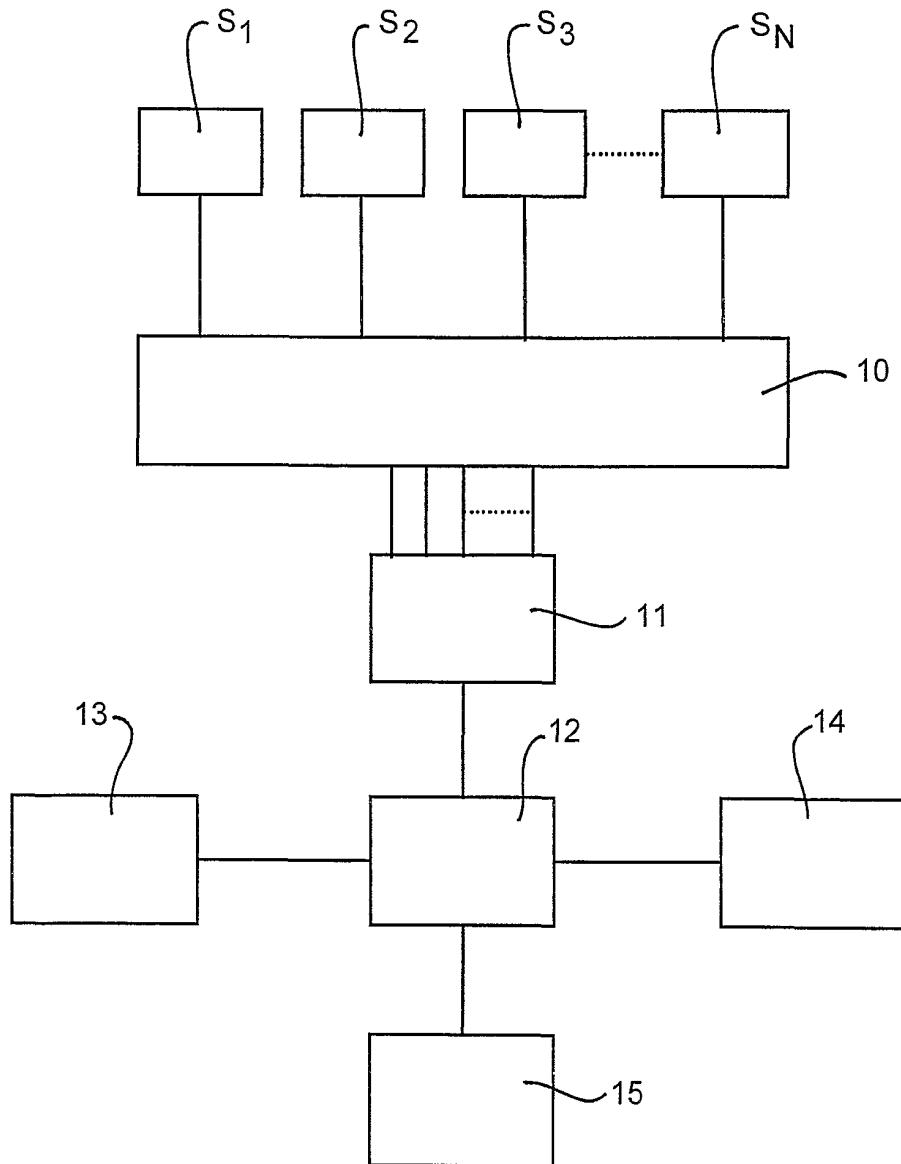


FIG 1

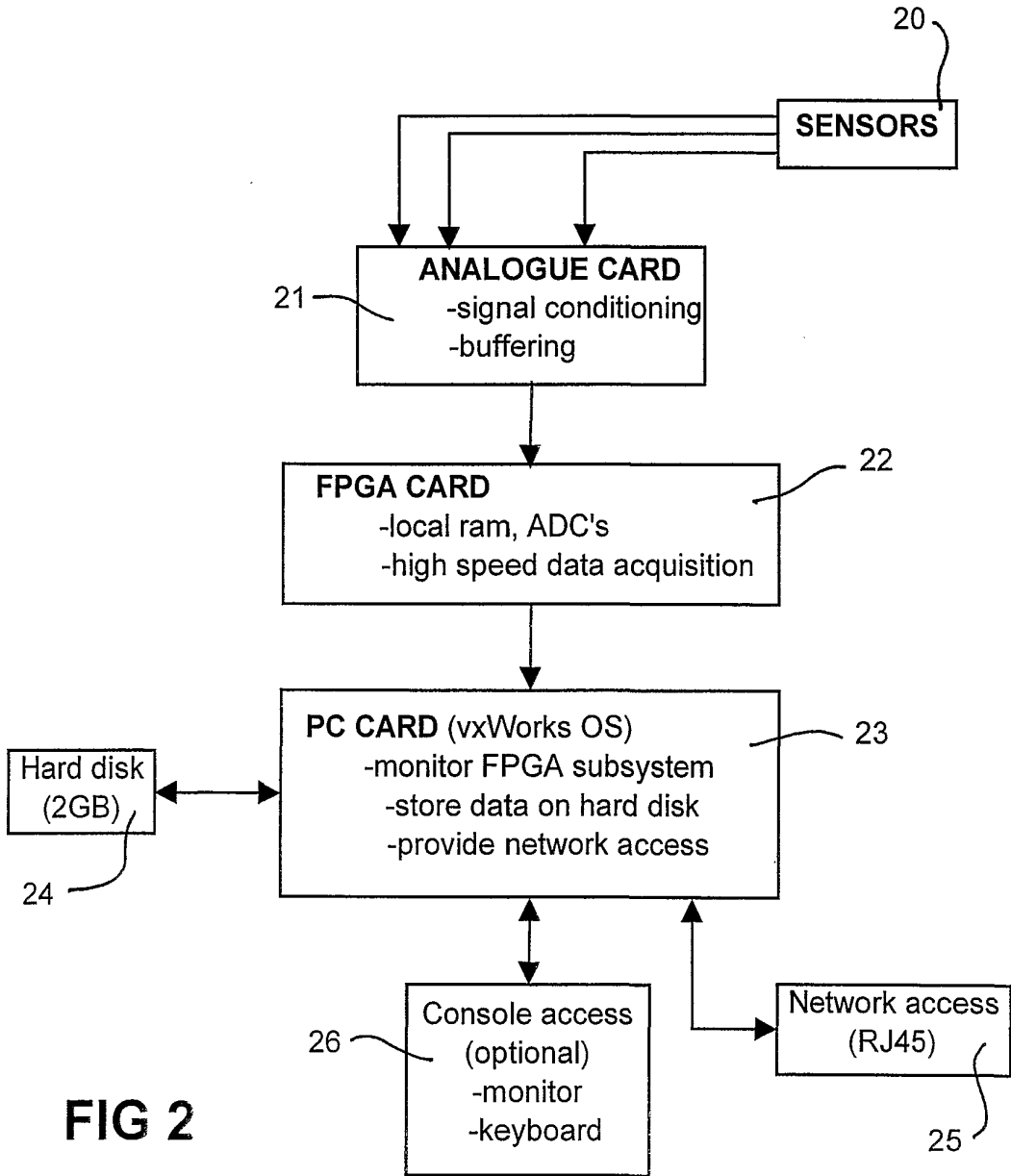


FIG 2

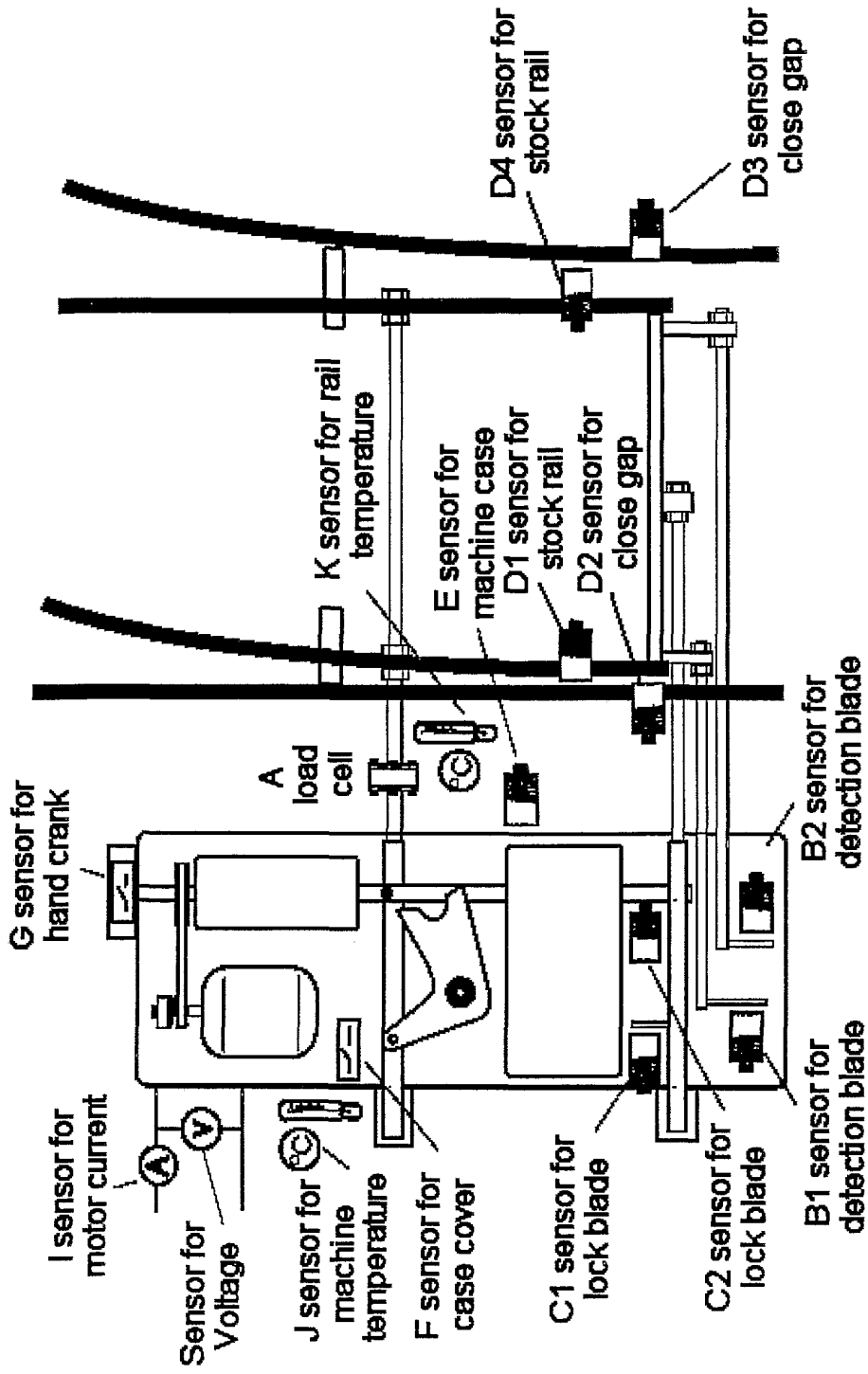


FIG 3

Sensor Ref	Location	Record	Type
A	Point M/c Drive Rod	Drive load/Thrust	Load Cell Strain Gauge
B1,B2	Detector Rods within point M/c	Linear displacement Det. Rods to M/c	Inductive Analogue
C1,C2	Facing Point Lock within point M/c	Linear displacement Lockblades to M/c	Inductive Analogue
D1	Left Hand Switch Rail	Linear Displacement LH Switch 'Closed'	Inductive Analogue
D2	Left Hand Switch Rail	Linear Displacement LH Switch 'Open'	Inductive Analogue
D3	Right Hand Switch Rail	Linear Displacement RH Switch 'Open'	Inductive Analogue
D4	Right Hand Switch Rail	Linear Displacement RH Switch 'Closed'	Inductive Analogue
E	Point Machine Casing	Linear Displacement M/c relative to track	Inductive Analogue
F	Point Machine Main Cover	Cover movement Open/Closed	Mech micro switch
G	Hand Crank	Hand Crank insertion/removal	Mech micro switch
H	Motor Control	Circuit integrity	100W Thick Film Res
I(nor)	Motor Control	Motor Current & Voltage driving 'Normal'	Resistor -4 Wire
I(rev)	Motor Control	Motor Current & Voltage driving 'Reverse'	Resistor -4 Wire
J	Point Machine	Surface Temperature	Thermistor
K	Rail	Surface Temperature	Thermistor

FIG 4

REFERENCES CITED IN THE DESCRIPTION

This list of references cited by the applicant is for the reader's convenience only. It does not form part of the European patent document. Even though great care has been taken in compiling the references, errors or omissions cannot be excluded and the EPO disclaims all liability in this regard.

Patent documents cited in the description

- FR 2797958 [0001]
- FR 2745543 [0001]